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Administration

Passenger Train-to-Freight Train Impact Test: Test Procedures, Instrumentation and Data

Office of Research and Development Washington, D.C. 20590

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Southeastern Pennsylvania Transit Authority (SEPTA) donated the cab-car used in the test, Long Island Railroad (LIRR) donated the M1 coach cars and AMTRAK donated the F40 locomotives.

Arthur D. Little designed the 1990's end-frame attached to the front end of the cab-car.

Executive Summary

A full-scale passenger train-to-freight train impact test was performed on January 31, 2002, at the Federal Railroad Administration's (FRA) Transportation Technology Center, Pueblo, Colorado, by Transportation Technology Center, Inc. (TTCI), a subsidiary of the Association of American Railroads (AAR).

The main results of the test are:

- The speed of impact, as measured by the laser speed trap, was 29.9 mph (i.e., within 0.3% of the desired speed of 30 mph)
- There was a large amount of damage to the leading cab-car, which climbed up onto the nose of the locomotive at an angle of about 20 degrees and then fell off to one side. The impact end-frame of the cab-car was completely separated from the center sill, with about 1/2 the length of the cab car being crushed.
- There was very little damage to the trailing coach cars, although all of them were derailed. There was about a 2 feet offset between the leading cab-car and the 2nd coach car and between the 2nd coach car and the 3rd coach car.
- The nose of the locomotive received very little damage, but the roof and windshield of the locomotive received some superficial damage. The locomotive and the hopper cars also derailed during the impact.
- The maximum longitudinal acceleration recorded on the center-sill of the lead cab-car was 125 g. When filtered using a low-pass filter with a corner frequency of 100 Hz, Fc = 100 Hz, the peak acceleration was reduced to 30 g.
- The maximum longitudinal acceleration recorded on the center-sill of the 2^{nd} coach car was 75 g. When filtered to Fc = 100 Hz, the peak acceleration was reduced to 20 g.
- The maximum longitudinal acceleration recorded on the center-sill of the 3^{rd} coach car was 20 g. When filtered to Fc = 100 Hz, the peak acceleration was reduced to 16 g.
- The maximum longitudinal acceleration recorded on the center-sill of the 4^{th} coach car was 25 g. When filtered to Fc = 100 Hz, the peak acceleration was reduced to 13 g.
- The maximum longitudinal acceleration recorded on the center-sill of the stationary locomotive was 400 g. (Filtered data was corrupted due to saturation effects)
- The maximum longitudinal acceleration recorded on the floor of the operator's cab in the stationary locomotive was 110 g. When filtered to Fc = 100 Hz, the peak acceleration was reduced to 50 g.

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The test was performed by colliding a passenger train made up of a Budd Company Pioneer-type cab-car, two M1 passenger cars provided by Long Island Railroad (LIRR), an instrumentation car (T-car) provided by the FRA, and a trailing locomotive provided by AMTRAK into a stationary freight train made up of a locomotive, also provided by AMTRAK, and two hopper cars.

The impact cab-car was fitted with a modified front end, designed by Arthur D. Little, Inc., to conform to 1990 standards. The impact locomotive had a modified hood and collision post fitted to comply with AAR Crashworthiness Standard S-580.

The purpose of the test was to measure the colliding equipment interaction and the amount of crush between the cars. Also to measure strains, accelerations, and displacements during the impact so that computational and kinematic models of the impact can be validated.

The seats were removed from the cab-car and the leading M1 car so that internal seat experiments could be installed. by another government contractor, Simula, who fitted two rows of seats in the cab-car and four rows of seats in the leading M1 car, all with Anthropomorphic Test Devices (ATD's) installed. They also fitted a one-person set with an ATD in the cab of the impact locomotive.

The Impact Test was performed by pushing the moving consist with a locomotive, releasing it at a pre-determined point at a pre-determined speed and then allowing it to roll along the track into the stationary locomotive and hopper cars. The release distance and the release speed were calculated from a series of calibration tests and computer simulations completed before the actual impact test.

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1.0 INTRODUCTION AND OBJECTIVES

Transportation Technology Center, Inc. (TTCI) performed a full-scale train-to-train impact test January 31, 2002, when a Budd Company Pioneer-type cab-car led train impacted a stationary Amtrak F40 locomotive led freight train at 29.9 mph. The moving consist included the cab-car, two LIRR M1 passenger cars, an instrumentation car (T-car), and a trailing Amtrak F40 locomotive. The stationary consist included a locomotive and two hopper cars, one loaded and one empty.

The purpose of the test was to measure the colliding equipment interaction and the amount of crush among the cars. Also to measure strains, accelerations, and displacements during the impact so that computational and kinematic models of the impact can be validated.

2.0 DESCRIPTION OF TEST VEHICLES

The test was conducted using a Budd Company Pioneer-type cab-car provided by the Southeastern Pennsylvania Transportation Authority (SEPTA), two M1 passenger cars provided by the Long Island Railroad (LIRR), a T-car provided by the Federal Railroad Administration (FRA), two F-40 locomotives provided by Amtrak, and two hopper cars provided by the FRA.

The impact cab-car was fitted with an end-frame designed to conform to 1990 standards. Arthur D. Little, Inc. designed this front end. The original seats were removed, along with other under-floor and ancillary equipment. Approximately 10,000 pounds of concrete was added, mostly under the floor in the center of the car, to make up for the weight of the missing equipment.

The seats were removed from one of the M1 cars so that the internal seat experiments could be installed, and some of the under-floor equipment was removed from both cars so that accelerometers could be mounted on the center sill. Both car bodies had some superficial damage, which was repaired and patched up with thin stainless steel sheets.

The impact locomotive was fitted with a modified hood and collision posts so that it complied with AAR Locomotive Crashworthiness Standard S-580.

The couplers were left installed at the impact ends of both the cab-car and the locomotive. Flat plates were welded to the front of each coupler in order to mount Tape Switches[™] to trigger the instrumentation at impact. An instrumented coupler was fitted between the cab-car and the leading M1 car.

Simula fitted two rows of three-place M-style seats in the rear of the cab-car, two rows of two-place Amtrak Inter-city seats in the front of the leading M1 car, and two rows of three-place M-style seats in the rear of the leading M1 car. They also fitted a one-person seat in the cab of the impact locomotive. (The description of these seat experiments and the resulting data are the subject of another report.)

A bike-rack, with a bike, was installed on a vertical face in the T-car.

The moving consist was made up of the cab-car, two M1 cars, the T-car and a trailing locomotive. It was not possible to seal all the brake pipes on the M1 cars, so none of the brakes on this consist was set to come on after impact.

The hand brakes were set during the impact on the stationary consist, which was made up of a F-40 locomotive and two hopper cars.

3.0 TEST METHODOLOGY

The test was performed at the FRA's Transportation Technology Center (TTC), Pueblo, Colorado, according to the procedures outlined in the Test Implementation Plan for the train-to-train test, Appendix A of this report.

The Impact Test was performed by pushing the test consist with a locomotive, releasing it at a pre-determined point, then letting it run along the track into the stationary consist. The release distance and the speed of the locomotive at release were calculated from a series of speed calibration tests carried out on the Precision Test Track (PTT) and over the actual test site (Figure 3.1). Simulation calculations were also performed using TOESTM (TTCI's train action model) based on the actual track profile. The target speed for the test was 30 mph.



Figure 3.1 Precision Test Track and Impact Test Track

4.0 RESULTS

4.1 Items Measured Before The Test

4.1.1 <u>Lengths</u>

Moving Consist

Length of cab-car (SEPTA245), buffer beam to buffer beam = 83.46 ft Length of leading M1 car (LIRR9614), buffer beam to buffer beam = 83.45 ft Length of trailing M1 car (LIRR9441), buffer beam to buffer beam = 83.37 ft Length of T-7 car, buffer beam to buffer beam = 83.64 ft Length of trailing locomotive (202) = 54.23 ft

Stationary Consist

Length of stationary locomotive (234) = 53.57 ft Length of leading hopper car (UP32022) = 49.25 ft Length of trailing hopper car (UP32057) = 49.28 ft

4.1.2 Weights

Moving Consist

Weight of cab-car (SEPTA245) = 75,014 lb Weight of leading M1 car (LIRR9614) = 73,427 lb Weight of trailing M1 car (LIRR9441) = 72,836 lb Weight of T-7 car = 148,944 lb Weight of trailing locomotive (202) = 267,054 lb

Total weight = 637,275 lb

Stationary Consist

Weight of stationary locomotive (234) = 244,584 lb Weight of leading hopper car (UP32022) = 312,598 lb Weight of trailing hopper car (UP32057) = 78,459 lb

Total weight = 635,641 lb

(Note: The accuracy of the weigh-bridge is within 50 lb)

4.1.3 Weather Conditions

The weather conditions just before the test:

- Temperature = $32^{\circ}F$
- Wind speed = 7 mph from the SW

4.1.4 Photographs Taken Before Test

Photographs showing the vehicles, just before the test, are shown in Figures 4.1.1, 4.1.2, and 4.1.3.



Figure 4.1.1 Cab-Car before Impact



Figure 4.1.2 Moving Consist Behind Cab-Car Before Impact



Figure 4.1.3 Stationary Consist Before Impact

4.2 ITEMS MEASURED DURING THE TEST

The following anomalies occurred with the data acquisition system:

- Three channels for the impact cab-car (B1) were not acquired due to trigger failure on Data Brick SN90002 (C1X, AR-tapeswitch, AL-tapeswitch)
- Seven channels on the 4th coach car (B4) were not acquired due to battery failure (C2X, C2Y, C2Z, C3X, C3Y, C3Z, BBZ)
- Eight channels for the impact cab-car were affected by periodic noise pulses that were superimposed on the valid signals. The fault was later traced to a faulty power supply module in Data Brick SN90068 (CSR3U, CSL3U, CSR3L, CSL3L, SSR1, SSR2, SSL2)

4.2.1 Speed

The moving consist was accelerated from rest by a locomotive and released at a point 1,500 feet from the front of the stationary locomotive. The speed of the consist just before impact, as measured by the laser based speed trap, was:

Laser 1	43.85 ft/s
Laser 2	43.85 ft/s
Average	43.85 ft/s = 29.9 mph

The amount of energy (E) dissipated during the impact can be calculated from the speed of the moving consist just before impact, $V_0 = 43.85$ ft/s, and the total weight of the moving consist, $M_0 = 637,275$ lb.

$$E = \frac{\frac{1}{2} \cdot M_0 V_0^2}{\frac{1}{2} \times 637,275 \times 43.85^2 / 32.2}$$

= 19.03 x 10⁶ ft.lb
= 25.8 MJ

4.2.2 Strains

The Data Bricks measuring strain were set for a sampling rate of 7,944.83 Hz, a pre-trigger of 2s and post-trigger of 6s.

The strain gauge time histories are presented in the following JPEG files on the attached Compact Disc (CD) in the file "Data Plot Files":

Impact cab-car	B1 Strain Gauge
Stationary Locomotive	SL Strain Gauge

All plots are shown for the following windows:

Full Period
$$= -2s$$
 to 4s

Zoom = -0.1s to 1s

The Test Implementation Plan in Appendix A shows the positions of the individual strain gauges.

The plots on the CD are presented in the following format (typical example):

B1_CSR1U Plot.JPG

Where:

B1 = vehicle, in this case the impact cab-car

CSR1U = particular strain gauge, in this case CS-R-1-U = Center Sill, Right, Position 1, Upper

4.2.3 Accelerations

The Data Bricks measuring acceleration were set for a sampling rate of 7,944.83 Hz, a pre-trigger of 2s and post-trigger of 6s.

The acceleration time histories are presented as JPEG files on the attached Compact Disc (CD) in the file "Data Plot Files":

Impact Cab-car	B1 Accelerometer
Second Coach Car (M1 car)	B2 Accelerometer
Third Coach Car (M1 car)	B3 Accelerometer
Fourth Coach Car $(T - car)$	B4 Accelerometer
Trailing Locomotive	BL Accelerometer
Stationary Locomotive	SL Accelerometer
Stationary Freight Cars	SH1&2 Accelerometer

The time histories are filtered with corner frequencies of 1,000 Hz (Fc = 1,000 Hz), 100 Hz (Fc = 100 Hz) and 25 Hz (Fc = 25 Hz).

All plots are shown for the following windows:

Full Period = -2s to 4s Zoom = -0.1s to 1s

The Test Implementation Plan in Appendix A shows the positions of the individual accelerometers.

The plots on the CD are presented in the following format (typical example):

B1_C1X_1000Hz_Plot.JPG

Where:

B1 = vehicle, in this case the impact cab-car

C1X = particular accelerometer, in this case C1X = Center Sill, Position 1, Xaxis

1000 Hz = Corner frequency of 1000Hz Full Period

4.2.4 **Displacements**

The vertical displacement across the secondary suspension of the cab-car and the two M1 cars were measured using string potentiometers between the car body and the truck.

The displacements (in each direction) between the cab-car trailing end coupler and the car body, the M1 car bodies and their couplers, and the T-car leading end coupler and car body were also measured using string potentiometers.

For the cab-car string potentiometers, the Data Brick sample rate was set to 3,972.41 Hz and for the 3rd coach car the sample rate was set at 3,980.99 Hz. For all other displacement measurements the Data Brick sample rate was set to 7,944.83 Hz. For all measurements the pre-trigger time was set to 2 s and the post-trigger time to 6 s.

The displacement time histories are presented as JPEG files on the attached Compact Disc (CD) in the file "Data Plot Files":

Impact Cab-car	B1 String Pot	
Second Coach Car (M1 car)	B2 String Pot	
Third Coach Car (M1 car)	B3 String Pot	
Fourth Coach Car (T – car)	B4 String Pot	

All plots are shown for the following windows:

Full Period= -2s to 4sZoom= -0.1s to 1s

The Test Implementation Plan in Appendix A describes where the displacement transducers were mounted. Essentially there were string potentiometers across each secondary suspension of the impact cab-car (B1), the second coach car (B2) and the third coach car (B3). String potentiometers were also fixed between the couplers and car bodies of the impact cab-car (B1) and the second coach car (B2), between the second coach car (B2) and the third coach car (B3) and the fourth coach car (B4). These string potentiometers were positioned to measure longitudinal, lateral and vertical displacements.

The plots on the CD for the displacements across the secondary suspensions are presented in the following format (typical example):

B1_AL_Plot.JPG

Where:

B1 = vehicle, in this case the impact cab-car

AL = displacement across secondary suspension at A-end (leading end), left side. The plots on the CD for the coupler displacements are presented in the following format (typical example):

B1_CBX_Plot.JPG

Where:

B1 = vehicle, in this case the impact cab-car CBX = coupler displacement at B-end (trailing end) in X-direction (longitudinal)

4.2.5 Longitudinal Velocity

The x-axis acceleration time histories for all the center sill accelerometers on all the moving cars have been integrated to give velocity and then plotted against time for the "Full" period, -2s to 4s, and are located in the file called "Moving Consist Velocities" on the attached CD. The Test Implementation Plan in Appendix A shows the positions of the accelerometers.

4.2.6 Longitudinal Force In Coupler

The Data Bricks were set for a sampling rate of 7,944.83 Hz, a pre-trigger of 2 s and post-trigger of 6 s.

The coupler at the trailing end of the impact cab-car was strain gauged and calibrated so that the longitudinal force could be measured. The coupler force time history is located in the file called "B-End Coupler Load" on the attached CD, for the "Full" period, -2s to 4s, and for the "Zoom" period, -0.1s to 1.0s.

4.2.7 High Speed And Video Photography

The Impact Test was visually recorded with 10 high-speed film cameras and 14 video cameras. Camera coverage was selected to provide views of both the left and right sides of the vehicle, overhead views, and an overall view of the impact.

The film and video camera positions are shown in Figure 4.2.1.



Figure 4.2.1 Camera Positions

Set-up sheets for the film camera are presented in Appendix B.

Two high-speed film cameras, F1 and F10, did not run due to a power failure.

One video camera, V9, did not run for an unknown reason.

4.3 ITEMS MEASURED AFTER THE TEST

Figure 4.3.1 shows the cars at the moment of impact. Figures 4.3.2, 4.3.3, and 4.3.4 show the cab-car and other passenger cars after impact. The second and third passenger cars after impact are shown in Figure 4.3.5. The locomotive after impact is shown in Figure 4.3.6. The relative positions of all the vehicles after impact are shown in diagrammatic form in Figure 4.3.7



Figure 4.3.1 Cars at Moment of Impact



Figure 4.3.2 Cab-Car after Impact



Figure 4.3.3 Moving Consist after Impact



Figure 4.3.4 Cab-Car after Impact



Figure 4.3.5 Second and Third Passenger Cars after Impact



Figure 4.3.6 Locomotive after Impact



Figure 4.3.7 Positions of Cars after Impact

5.0 CONCLUSIONS

- The speed of the moving consist at impact with the stationary locomotive was 29.9 mph. This was within 0.3% of the desired speed of 30 mph.
- There was a large amount of damage to the leading cab-car, which climbed up onto the nose of the locomotive at an angle of about 20 degrees and then fell off to one side. The impact end-frame of the cab-car was completely separated from the center sill with about 1/2 the length of the cab car being crushed.
- There was very little damage to the trailing coach cars although all of them were derailed. There was about a 2 feet offset between the leading cab-car and the 2nd coach car and between the 2nd coach car and the 3rd coach car.
- The nose of the locomotive received very little damage, but the roof and windshield of the locomotive received some superficial damage. The locomotive and the hopper cars remained on the track.
- The maximum longitudinal acceleration recorded on the center-sill of the lead cab-car was 125 g at position C-3. When filtered to Fc = 100 Hz, the peak acceleration was reduced to 30 g.
- The maximum longitudinal acceleration recorded on the center-sill of the 2^{nd} coach car was 75 g at position C-2. When filtered to Fc = 100 Hz, the peak acceleration was reduced to 20 g.

- The maximum longitudinal acceleration recorded on the center-sill of the 3^{rd} coach car was 20 g at position C-1. When filtered to Fc = 100 Hz, the peak acceleration was reduced to 16 g.
- The maximum longitudinal acceleration recorded on the center-sill of the 4^{th} coach car was 25 g at position C-1. When filtered to Fc = 100 Hz, the peak acceleration was reduced to 13 g.
- The maximum lateral acceleration recorded on the center-sill of the lead cab-car was 125 g at position C-2. When filtered to Fc = 100 Hz, the peak lateral acceleration was reduced to 15 g.
- The maximum lateral acceleration recorded on the center-sill of the 2nd coach car was 85 g at position C-6. When filtered to Fc = 100 Hz, the peak lateral acceleration was reduced to 40 g.
- The maximum lateral acceleration recorded on the center-sill of the 3rd coach car was 30 g at position C-4. When filtered to Fc = 100 Hz the peak lateral acceleration was reduced to 9 g.
- The maximum lateral acceleration recorded on the center-sill of the 4^{th} coach car was 30g at position C-1. When filtered to Fc = 100 Hz the peak lateral acceleration was reduced to 4 g.
- The maximum vertical acceleration recorded on the center-sill of the lead cab-car was 125 g at position C-3. When filtered to Fc = 100 Hz, the peak vertical acceleration was reduced to 30 g.
- The maximum vertical acceleration recorded on the A-bogie of the lead cab-car was 125 g. When filtered to Fc = 100Hz the peak vertical acceleration was reduced to 75 g.
- The maximum vertical acceleration recorded on the center-sill of the 2nd coach car was 75 g at position C-2. When filtered to Fc = 100 Hz the peak acceleration was reduced to 20 g.
- The maximum vertical acceleration recorded on the A-bogie of the 2^{nd} coach car was 50 g. When filtered to Fc = 100Hz, the peak vertical acceleration was reduced to 15 g.
- The maximum vertical acceleration recorded on the center-sill of the 3rd coach car was 20 g at position C-1. When filtered to Fc = 100 Hz, the peak vertical acceleration was reduced to 16 g.
- The maximum vertical acceleration recorded on the A-bogie of the 3^{rd} coach car was 25 g. When filtered to Fc = 100 Hz, the peak vertical acceleration was reduced to 12 g.
- The maximum vertical acceleration recorded on the center-sill of the 4^{th} coach car was 25 g at position C-1. When filtered to Fc = 100 Hz, the peak vertical acceleration was reduced to 13 g.

- The maximum vertical acceleration recorded on the A-bogie of the 4th coach car was 24 g. When filtered to Fc = 100 Hz, the peak vertical acceleration was reduced to 10 g.
- The maximum longitudinal acceleration recorded on the center-sill of the stationary locomotive was 400 g at position C-1. (Filtered data corrupted due to saturation effects)
- The maximum lateral acceleration recorded on the center-sill of the stationary locomotive was 200 g at position C-1. (Filtered data corrupted due to saturation effects)
- The maximum vertical acceleration recorded on the center-sill of the stationary locomotive was 380 g at position C-1. When filtered to Fc = 100 Hz, the peak vertical acceleration was reduced to 50 g.
- The maximum longitudinal acceleration recorded on the floor of the operator's cab in the stationary locomotive was 110 g. When filtered to Fc = 100 Hz, the peak acceleration was reduced to 50 g.
- The maximum lateral acceleration recorded on the floor of the operator's cab in the stationary locomotive was 60 g. When filtered to Fc = 100 Hz, the peak lateral acceleration was reduced to 30 g.
- The maximum vertical acceleration recorded on the floor of the operator's cab in the stationary locomotive was 105 g. When filtered to Fc = 100 Hz, the peak vertical acceleration was reduced to 50 g.
- The maximum longitudinal acceleration recorded in the first stationary hopper car was 50 g. When filtered to Fc = 100 Hz, the peak acceleration was reduced to 18 g.
- The maximum longitudinal acceleration recorded in the second stationary hopper car was 30 g. When filtered to Fc = 100 Hz, the peak acceleration was reduced to 5 g.
- A peak load of more than 900,000 pounds was measured in the instrumented coupler between the cab-car and the 2nd coach car.
- The bike and its rack remained intact during the impact.

APPENDIX A: Test Implementation Plan

Test Implementation Plan for Cab-Car to Locomotive Impact Test

Barrie V. Brickle January 18, 2002 Version 3.0

1.0 Purpose

To run a cab car, four coupled passenger cars and a trailing locomotive into a stationary locomotive led freight train with two loaded hopper cars on level tangent track at an impact speed of approximately 30 mph. Computer simulations show that the "stationary" locomotive will move back 100 feet on impact, and that the leading passenger car will crush by approximately 14 feet. The cab-car, passenger cars and locomotives will be instrumented to measure material strains, structural accelerations, suspension displacements, coupler forces and coupler displacements throughout the vehicles in sufficient quantity to allow correlation with analytical predictions.

2.0 Requirements

To impact a cab-car, four coupled passenger cars and a locomotive into a stationary locomotive led freight train at an impact speed of 30 mph (+ or -5 mph).

3.0 Test Cars

The test will be conducted using a cab-car provided by SEPTA, four passenger cars provided by Long Island Railroad and locomotives provided by AMTRAK.

The cab-car will be modified to bring it up to 1990 standards by fitting a re-designed front end. A load test will be performed on the cab-car to show that it conforms to 1990's standards.

The stationary locomotive will be modified to bring the structure up to AAR Locomotive Crashworthiness Standard S-580. This will involve modifying the collision posts, short hood and anti-climber.

The cab-car and passenger cars will be modified internally so that a number of seat configurations can be tested. The stationary locomotive will have one interior test. All the interior experiments will be provided by SIMULA.

Ballast will be added to the test cab-car and passenger cars to replace the seats and other equipment removed from them before the test. The freight cars will be loaded with ballast.

4.0 Test Method

The test will be performed at the TTC by impacting the coupled passenger test cars into the stationary locomotive led freight train at a speed of 30 mph. The impact test will be carried out by pushing the test cars and trailing locomotive with another locomotive and then releasing them and allowing them to roll along the track and into the stationary locomotive and loaded freight cars. The release distance, and the speed of the locomotive at the release point, will be determined from a series of calibration runs carried out before the locomotive led freight train is put in place.

An on-board radar speed measuring system will be used for speed calibration of the test cars. The ambient temperature and wind speed will be measured during the calibration tests and during the actual test. A laser speed trap will be used to measure the speed of the test cars just before impact.

On-board instrumentation will record accelerations, displacements and strains at various points on the test cars, locomotives and freight cars during and after the impact. High speed film cameras and video cameras will be used to record both the impact between the lead cab-car and the locomotive and between the passenger cars themselves.

5.0 Measured Items

The length and weight of each vehicle will be measured before the test:

Strains and accelerations will be measured during the test using a battery powered onboard data acquisition system which will provide excitation to the strain gages and accelerometers, analog anti-aliasing filtering of the signals, analog-to-digital conversion and recording. Data acquisition will be in accordance with SAE J211/1,Instrumentation for Impact Tests (revised March 1995). Data from each channel will be recorded at a sample rate of 12,800 Hz. All data will be synchronized with a time reference applied to all systems simultaneously at the time of impact. The time reference will come from a closure of a tape switch on the front of the impacting cab-car. The following items will be measured during the test:

- 1. The speed of the cab-car just before impact using a laser based speed trap.
- 2. Longitudinal strains at draft sills and center sills of the impacting cabcar (see Figure 5.1)(12 strain gages)
- 3. Longitudinal strains at the side sills and cant rails of the impacting cab-car (see Figure 5.2)(12 strain gages)
- 4. Accelerations of draft sills, center sill and left and right side sills of the impacting cab-car (see Figure 5.3)(23 accelerometers)
- 5. Accelerations of each truck of the impacting cab-car in the longitudinal, vertical and lateral directions (6 accelerometers)
- 6. Accelerations of draft sills, center sill and left and right side sills of the second coach car (see Figure 5.4)(17 accelerometers)
- 7. Accelerations of each truck of the second coach car in the lateral direction (2 accelerometers)

- 8. Accelerations of draft sills and center sill of the third coach car (see Figure 5.5)(11 accelerometers)
- 9. Accelerations of each truck of the third coach car in the lateral direction (2 accelerometers)
- 10. Accelerations of center sill of the fourth coach car (see Figure 5.6)(9 accelerometers)
- 11. Accelerations of each truck of the fourth coach car in the lateral direction (2 accelerometers)
- 12. Accelerations of center sill of the fifth coach car (see Figure 5.7)(9 accelerometers)
- 13. Accelerations of each truck of the fifth coach car in the lateral direction (2 accelerometers)
- 14. Accelerations of the main sill of the trailing locomotive (see Figure 5.8)(9 accelerometers)
- 15. Accelerations of each truck of the trailing locomotive in the lateral direction (2 accelerometers)
- 16. Accelerations of the main sill of the stationary locomotive (see Figure 5.9)(9 accelerometers)
- 17. Accelerations of each truck of the stationary locomotive (6 accelerometers)
- 18. Acceleration of the Operator's Cab of the stationary locomotive (see Figure 5.10)(3 accelerometers)
- 19. Longitudinal strains on the main sill of the stationary locomotive (see Figure 5.11)(12 strain gages)
- 20. Longitudinal accelerations of center sill of the first and second stationary freight cars (see Figure 5.12)(4 accelerometers)
- 21. Displacement across each secondary suspension of the impacting cabcar (4 string potentiometers)
- 22. Displacement across each secondary suspension of the first coach car (4 string potentiometers).
- 23. Displacement across each secondary suspension of the second coach car (4 string potentiometers)
- 24. Lateral and vertical displacements of couplers relative to car body between impacting cab-car and first coach car (3string potentiometers on each coupler, ie. total of 6 string potentiometers).
- 25. Lateral and vertical displacements of couplers relative to car body between first coach car and second coach car (3string potentiometers on each coupler, ie. total of 6 string potentiometers)
- 26. Lateral and vertical displacements of couplers relative to car body between second coach car and third coach car (3string potentiometers on each coupler, ie. total of 6 string potentiometers)
- 27. Longitudinal strain on coupler between impacting cab-car and first coach car (1 strain gage bridge)
- 28. Tape switches on each corner post of impact end of leading cab-car (2 tape switches).

This amounts to a total of 185 channels

High-speed film cameras and video cameras will be used to record the impact. A reference signal will be placed on the film so that analysis of the film after the event will give the velocity and displacement of each vehicle during impact.

The length of each vehicle will be measured after the test.

6.0 Instrumentation

6.1 Strain measurements

6.1.1 Strain measurements, Impact Cab-Car

Figure 1 shows the general arrangement of strain gages on the Center Sill.

Table 1 lists the locations and strain gage types for all the strain gages on the center sill.

Location	Strain Gage	Channel	••••••
CS-R-1-U	Standard	1	
CS-L-1-U	Standard	2	
CS-R-1-L	Standard	3	
CS-L-1-L	Standard	4	
CS-R-2-U	Standard	5	
CS-L-2-U	Standard	6	
CS-R-2-L	Standard	7	
CS-L-2-L	Standard	8	
CS-R-3-U	Standard	9	
CS-L-3-U	Standard	10	
CS-R-3-L	Standard	11	
CS-L-3-L	Standard	12	

Table 1 Impact Cab-Car, Strain gage location and type, Center Sill

Figure 2 shows the general arrangement of strain gages on the Side Sill and Cant Rail.

Table 2 lists the locations and strain gage types for all the strain gages on the side sills and cant rails.

Location	Strain Gage	Channel	
SS-R-1	Standard	1	
SS-L-1	Standard	2	
SS-R-2	Standard	3	
SS-L-2	Standard	4	
SS-R-3	Standard	5	
SS-R-3	Standard	6	
CR-R-1	Standard	7	
CR-L-1	Standard	8	
CR-R-2	Standard	9	
CR-L-2	Standard	10	
CR-R-3	Standard	11	
CR-L-3	Standard	12	

Table 2 Impact Cab-Car, Strain gage location and type, Side Sill and Cant Rail

6.1.2 Strain Measurements, Stationary Locomotive

Figure 11 shows the general arrangement of strain gages on the Main Sill of the Locomotive.

Table 3 lists the locations and strain gage types for all the strain gages on the main sill of the locomotive.

Location	Strain Gage	Channel	
MS-R-1-U	Standard	1	
MS-L-1-U	Standard	2	
MS-R-1-L	Standard	3	
MS-L-1-L	Standard	4	
MS-R-2-U	Standard	5	
MS-L-2-U	Standard	6	
MS-R-2-L	Standard	7	
MS-L-2-L	Standard	8	
MS-R-3-U	Standard	9	
MS-L-3-U	Standard	10	
MS-R-3-L	Standard	11	
MS-L-3-L	Standard	12	

Table 3. Stationary Locomotive, Strain gage location and type, MainSill

6.1.3 Coupler Force

The coupler will be strain gauged with a single gage bridge measuring the longitudinal force.

6.2 Acceleration measurements

The car-bodies gross and flexible motions will be measured using accelerometers. The gross motions of the car-bodies are the longitudinal, lateral, and vertical translational displacements, as well as the pitch, yaw and roll angular displacements. The flexible modes include vertical and lateral bending as well as torsional displacement about axis of the body. Measurements of these motions are required to fully characterize the secondary collision environment.

All the accelerometers are critically damped. The accelerometers will be calibrated prior to installation. The accelerometers posses natural frequencies sufficiently high to meet the requirements of SAE J211/1, *Instrumentation for Impact Test (Revised MAR95)*, class 1000, which requires that the frequency response is essentially flat to 1000 Hz.

6.2.1 Accelerometer measurements, Impact Cab-Car

Figure 3 shows the general arrangement of accelerometers on the Impact Cab-Car.

Table 4 lists the accelerometer locations, accelerometer types, and data channels for the Impact Cab-Car.

Location	Accelerometer	Measurement	Measurement		Channel	
			<u> </u>			
	Single axis	Longitudinal	<u>X</u>	1	1,000G	
0-2	I hree axis	Longitudinal	<u> </u>	2	1,000G	
		Lateral	Y	3	100G	
		Vertical	Z	4	400G	
C-3	Two axis	Longitudinal	Χ	5	400G	
		Vertical	Z	6	400G	
C-4	Three axis	Longitudinal	Х	7	400G	
		Lateral	Y	8	100G	
		Vertical	Z	9	200G	
C-5	Two axis	Longitudinal	Х	10	400G	
		Vertical	Z	11	200G	
C-6	Three axis	Longitudinal	Х	12	400G	
		Lateral	Y	13	100G	
		Vertical	Z	14	200G	
C-7	Single axis	Longitudinal	Х	15	400G	
R-2	Single axis	Vertical	Z	16	400G	
R-4	Two axis	Longitudinal	Х	17	400G	
		Vertical	Z	18	200G	
R-6	Single axis	Vertical	Z	19	200G	
L-2	Single axis	Vertical	Z	20	400G	
L-4	Two axis	Longitudinal	Х	21	400G	
		Vertical	Z	22	200G	
L-6	Single axis	Vertical	Z	23	200G	
B-1 (Bogie)	Three axis	Longitudinal	Х	24	400G	
		Lateral	Y	25	100G	
		Vertical	Ζ	26	400G	
B-2 (Bogie)	Three axis	Longitudinal	Х	27	400G	
		Lateral	Y	28	100G	
		Vertical	Z	29	200G	

Table 4 Impact Cab-Car, Accelerometers

6.2.2 Accelerometer measurements, Second Coach Car

Figure 4 shows the general arrangement of accelerometers on the Second Coach Car.

Table 5 lists the accelerometer locations, accelerometer types, and data channels for the Second Coach Car.

Location	Accelerometer	Measurement		Channe	
C-1	Single axis	Longitudinal	Х	1	200G
C-2	Three axis	Longitudinal	Х	2	200G
		Lateral	Y	3	100G
		Vertical	Z	4	200G
C-3	Single axis	Longitudinal	Х	5	200G
C-4	Three axis	Longitudinal	Х	6	200G
		Lateral	Y	7	100G
		Vertical	Z	8	200G
C-5	Single axis	Longitudinal	Х	9	200G
C-6	Three axis	Longitudinal	Х	10	200G
		Lateral	Y	11	100G
		Vertical	Z	12	100G
C-7	Single axis	Longitudinal	Х	13	200G
R-4	Two axis	Longitudinal	Х	14	200G
		Vertical	Z	15	100G
L-4	Two axis	Longitudinal	Х	16	200G
		Vertical	Z	17	100G
B-1 (Bogie)	Single axis	Vertical	Z	18	100G
B-2 (Bogie)	Single axis	Vertical	Z	19	100G

 Table 5 Second Coach Car, Accelerometers

6.2.3 Accelerometer measurements, Third Coach Car

Figure 5 shows the general arrangement of accelerometers on the Third Coach Car.

Table 6 lists the accelerometer locations, accelerometer types, and data channels for the Third Coach Car.

Location	Accelerometer	Measurement	Channel		
C-1	Single axis	Longitudinal	Х	1	100G
C-2	Three axis	Longitudinal	Х	2	100G
		Lateral	Y	3	25G
		Vertical	Z	4	50G
C-3	Three axis	Longitudinal	Х	5	100G
		Lateral	Y	6	25G
		Lateral	Z	7	50G
C-4	Three axis	Longitudinal	Х	8	100G
		Lateral	Y	9	25G
		Vertical	Z	10	50G
C-5	Single axis	Longitudinal	Х	11	100G
B-1 (Bogie)	Single axis	Vertical	Z	12	50G
B-2 (Bogie)	Single axis	Vertical	Z	13	50G

 Table 6 Third Coach Car, Accelerometers

6.2.4 Accelerometer measurements, Fourth Coach Car

Figure 6 shows the general arrangement of accelerometers on the Fourth Coach Car.

Table 7 lists the accelerometer locations, accelerometer types, and data channels for the Fourth Coach Car.

Location	Accelerometer	Measurement	Channel		
C-1	Three axis	Longitudinal	Х	1	100G
		Lateral	Y	2	25G
		Vertical	Z	3	50G
C-2	Three axis	Longitudinal	Х	4	100G
		Lateral	Y	5	25G
		Vertical	Z	6	50G
C-3	Three axis	Longitudinal	Х	7	100G
		Lateral	Y	8	25G
		Vertical	Z	9	50G
B-1 (Bogie)	Single axis	Vertical	Z	10	50G
B-2 (Bogie)	Single axis	Vertical	Z	11	50G

Table 7 Fourth Coach Car, Accelerometers

6.2.5 Accelerometer measurements, Fifth Coach Car

Figure 7 shows the general arrangement of accelerometers on the Fifth Coach Car.

Table 8 lists the accelerometer locations, accelerometer types, and data channels for the Fifth Coach Car.

Location	Accelerometer	Measurement	Channel		
C-1	Three axis	Longitudinal	Х	1	100G
		Lateral	Y	2	25G
		Vertical	Z	3	50G
C-2	Three axis	Longitudinal	Х	4	100G
		Lateral	Y	5	25G
		Vertical	Z	6	50G
C-3	Three axis	Longitudinal	Х	7	100G
		Lateral	Y	8	25G
		Vertical	Z	9	50G
B-1 (Bogie)	Single axis	Vertical	Z	10	50G
B-2 (Bogie)	Single axis	Vertical	Z	11	50G

Table 8 Fifth Coach Car, Accelerometers

6.2.6 Accelerometer measurements, Trailing Locomotive

Figure 8 shows the general arrangement of accelerometers on the Trailing Locomotive.

Table 9 lists the accelerometer locations, accelerometer types, and data channels for the Trailing Locomotive.

Location	Accelerometer	Measurement	Channel		
C-1	Three axis	Longitudinal	Х	1	100G
		Lateral	Y	2	25G
		Vertical	Z	3	50G
C-2	Three axis	Longitudinal	Х	4	100G
		Lateral	Y	5	25G
		Vertical	Z	6	50G
C-3	Three axis	Longitudinal	Х	7	100G
		Lateral	Y	8	25G
		Vertical	Z	9	50G
B-1 (Bogie)	Single axis	Vertical	Z	10	50G
B-2 (Bogie)	Single axis	Vertical	Z	11	50G

Table 9 Trailing Locomotive, Accelerometers

6.2.7 Accelerometer measurements, Stationary Locomotive

Figure 9 shows the general arrangement of accelerometers on the Trailing Locomotive.

Table 10 lists the accelerometer locations, accelerometer types, and data channels for the Trailing Locomotive.

Location	Accelerometer	Measurement		Channel	
C-1	Three axis	Longitudinal	Х	1	400G
		Lateral	Y	2	200G
		Vertical	Z	3	400G
C-2	Three axis	Longitudinal	Х	4	400G
		Lateral	Y	5	200G
		Vertical	Z	6	400G
C-3	Three axis	Longitudinal	Х	7	400G
		Lateral	Y	8	200G
		Vertical	Z	9	400G
B-1 (Bogie)	Three axis	Longitudinal	Х	10	400G
		Lateral	Y	11	200G
		Vertical	Z	12	200G
B-2 (Bogie)	Three axis	Longitudinal	Х	13	400G
		Lateral	Y	14	200G
		Vertical	Z	15	200G
Operator's Cab	Three axis	Longitudinal	Х	16	400G
1		Lateral	Y	17	200G
		Vertical	Z	18	400G

Table 10 Stationary Locomotive, Accelerometers

6.2.8 Accelerometer measurements, First Stationary Freight Car

Figure 10 shows the general arrangement of accelerometers on the First Stationary Freight Car.

Table 11 lists the accelerometer locations, accelerometer types, and data channels for the First Stationary Freight Car.

Location	Accelerometer	Measurement	Channel		
C-1	Single axis	Longitudinal	Х	1	100G
C-2	Single axis	Longitudinal	Х	2	100G
	Table 11 Einst Otations	Englated Anna			

Table 11 First Stationary Freight Car, Accelerometers

6.2.9 Accelerometer measurements, Second Stationary Freight Car

Figure 10 shows the general arrangement of accelerometers on the Second Stationary Freight Car.

Table 12 lists the accelerometer locations, accelerometer types, and data channels for the Second Stationary Freight Car.

Location	Accelerometer	Measurement		Channel	
C-1	Single axis	Longitudinal	Х	1	100G
C-2	Single axis	Longitudinal	Х	2	100G

Table 12 Second Stationary Freight Car, Accelerometers

6.3 String Potentiometers

Four string potentiometers will be fixed across each secondary suspension on the impacting cab-car, second coach car and third coach car between body bolster and bogie bolster to measure the relative vertical displacement (Total of 12 string potentiometers).

Six string potentiometers will be fixed between the couplers and car bodies of the impacting cab-car and second coach car, between the second coach car and third coach car and between the third coach car and fourth coach car, to measure lateral and vertical displacements (Total of 18 potentiometers).

6.4 High-speed and real-time photography

Ten high-speed film cameras and fourteen video cameras will document the impact test. The cameras will be located either side of the impact point between the cab-car and the locomotive and either side of the intersection between the impact cab-car and first coach car, the first coach car and second coach car and second coach car and third coach car. Other cameras will be located looking along the passenger train and looking down on the impact point from overhead. All the cameras are equipped with sights that allow the photographer to view the expected image. The final siting of cameras will be carried out at the time of camera setup. Adjustments will be made, if necessary, to achieve the optimum views.

A 100 Hz reference signal will be placed on the film so that accurate frame speed can be determined for film analysis. An electronic signal generator provides the calibrated 100-

Hz pulse train to light emitting diodes (LEDs) in the high-speed cameras. Illumination of the LEDs exposes a small red dot on the edge of the film, outside the normal field of view. During film analysis, the precise film speed is determined from the number of frames and fractions thereof that pass between two adjacent LED marks. Battery powered on-board lights will illuminate the on-board camera view. Battery packs use 30-v NiCad batteries.

Color negative film for the ground-based cameras will be Kodak 16-mm 7246, ISO 250, for daylight on 100-ft spools. Film speed will be pushed in processing if necessary to compensate for light conditions at test time.

Four-in. diameter targets will be placed on the vehicles and the ground to facilitate posttest film analysis to determine speed and displacement during the test. The targets are divided into four quadrants with adjacent colors contrasting to provide good visibility. At least three targets will be placed on each side of each vehicle and the ground. During film analysis, the longitudinal and vertical coordinates of the targets are determined from projections on a film analyzer on a frame-by-frame basis. The distances between the targets, which are known from pre-test measurements, provide distance reference information for the film analysis. The differences in locations between vehicle-mounted targets and ground-based targets quantify the motion of the vehicle during the test. By taking the position differences between vehicle-mounted and ground-based targets, the effects of film registration jitter in the high-speed cameras are minimized. The 100-Hz LED reference marks provide an accurate time base for the film analysis. Test vehicle position is determined directly as indicated above, and vehicle speed is determined by dividing the displacement between adjacent frames by the time difference between the adjacent frames. If necessary, smoothing is applied to the displacement and speed data to compensate for digitization and other uncertainties.

The ground-based cameras will be started simultaneously from a central relay box triggered manually. The cameras running at a nominal speed of 500 frames per second will run for about eight seconds before the100-ft film is entirely exposed.

6.5 Data Acquisition

Twenty-five, 8-channel battery-powered on-board data acquisition systems will provide excitation to the strain gages and accelerometers, analog anti-aliasing filtering of the signals, analog-to-digital conversion, and recording. Data acquisition will be in compliance with SAE J211. Data from each channel will be recorded at 12,800 Hz. Parallel redundant systems will be used for all accelerometer channels. Data recorded on the four systems will be synchronized with a time reference applied to all systems simultaneously at the time of impact. The time reference will come from closure of the tape switches on the front of the test vehicle. The data acquisition systems are GMH Engineering Data Brick Model II. Each Data Brick is ruggedized for shock loading up to at least 100 g. On-board battery power will be provided by GMH Engineering 1.7 A-HR 14.4 volt NiCad Packs. Tape Switches, Inc., model 1201-131-A tape switches will provide event markers.

Software in the Data Brick will be used to determine zero levels and calibration factors rather than relying on set gains and expecting no zero drift.

6.6 Tape Switches

Tape Switches will be installed on the coupler of the impacting cab-car and the coupler of the locomotive. Closure of these switches at impact will indicate contact between the cabcar and locomotive. The switch closures will trigger each Data Brick. The tape switches are manufactured by the Tapeswitch Corporation, model 1201-131-A.

Tape switches will also be mounted on the corner posts of the impacting cab-car to indicate the time of contact with the locomotive.

6.7 Speed Trap

A dual channel speed trap will accurately measure the impact speed of the cab-car when it is within 0.5 meter of the locomotive. The speed trap is a GMH Engineering Model 400, 4 Interval Precision Speed Trap with an accuracy of 0.1%. Passage of a rod affixed to the vehicle will interrupt laser beams a fixed and known distance apart. The first interruption starts a precision counter, and the second interruption stops the counter. Speed is calculated from distance and time. Tentatively, the rod will be attached at the aft end of the impact cab-car. Final rod location will be determined prior to installation.

7.0 Test Procedure

- (1) The lead cab-car will be modified to bring it up to current FRA standards by strengthening the corner posts and collision posts.
- (2) The stationary locomotive will be modified to bring the structure up to AAR Locomotive Crashworthiness Standard S-580. This will involve modifying the collision posts, short hood and anti-climber.
- (3) The cab-car and passenger cars will be modified internally with the appropriate seating arrangements required for the test.
- (4) Strain gages will be attached on the center sills, side sills and cant rails of the cabcar bodies.
- (5) Strain gages will be attached to the stationary locomotive.
- (6) The coupler will be strain gauged with a single gage bridge measuring the longitudinal force.
- (6) Speed calibration runs will be carried out using the test cars. The test cars will pushed by a locomotive and then released at points of varying distance from the impact point. The speed of the test cars will be measured as they pass the impact point, using a laser speed trap. These runs will be carried out at different ambient temperatures and wind speeds. Having passed the impact point, the test cars will be stopped by a locomotive catching them up, catching the coupler, and then slowing down and bringing the cars back to the start point. A calibration chart of speed versus distance for different ambient temperatures and wind speeds will be produced from these tests
- (7) The test equipment, including the accelerometers and data acquisition system will be mounted on the test vehicles. The strain gages will be connected to the data acquisition system and tested.

- (8) The cameras will be set up.
- (9) The length and weight of each vehicle will be measured just prior to the test.
- (10) All instruments will be calibrated and a zero reading carried out.
- (11) A trial low speed soft impact (less than 1 mph) of the test cars will be carried out into the locomotive to confirm all the instruments work properly.
- (12) The instruments will be re-calibrated, the Tape Switches replaced and the test cars pulled back.
- (13) The test cars will pushed by a locomotive and released at the appropriate distance from the stationary locomotive, triggering the cameras just before impact.
- (14) The instrumentation will be triggered on impact.
- (15) Visual inspection of the car bodies will be carried out after impact. Still photographs will be taken of all the vehicles.
- (16) The data will be downloaded onto lap-top computers from the on-board data acquisition system.
- A checklist will be utilized for the actual test, based on the above list, which will be signed by key personnel as each task is completed.

8.0 Data Analysis

8.1 Data Post Processing

Each data channel will be offset adjusted in post processing. The procedure is to average the data collected just prior to the test vehicle's impact with the barrier and subtract the offset from the entire data set for each channel. It is expected that between 0.05 and 0.50 s of pre-impact data will be averaged to determine the offsets. The precise duration of the averaging period cannot be determined with certainty until the data are reviewed. The offset adjustment procedure assures that the data plotted and analyzed contains impact-related accelerations and strains but not electronic offsets or steady biases in the data. The post-test offset adjustment is independent of, and in addition to, the pre-test offset adjustment made by the data acquisition system.

Plots of all data channels recorded and combinations of data channels will be produced as described below. Post-test filtering of the data will be accomplished with a two-pass phaseless four-pole digital filter algorithm consistent with the requirements of SAE J211. In the filtering process, data are first filtered in the forward direction with a two-pole filter. The first pass of the filtering process introduces a phase lag in the data. In the next pass, the data are filtered in the reverse direction with the same filter. Because the data are filtered in the reverse direction, a phase lead is introduced into the data. The phase lead of the reverse-direction filtering cancels the phase lag from the forward-direction filtering. The net effect is to filter the data without a change in phase with a four-pole filter.

8.2 Data Output

Every channel as recorded (raw data) will be plotted against time The acceleration records during the impacts will be plotted against time The longitudinal acceleration will be integrated and the derived velocity plotted against time. The longitudinal velocity will be integrated to give the crush displacement against time. The longitudinal accelerations at the center of gravity of the car body will be averaged and multiplied by the mass of the car body to give the force against time during the impact.

The strain gage time histories will be presented

All data recorded by the Data Bricks, and the derived values mentioned above, will be presented to the FRA in digital form on a Zip disc as well as on paper. The film from each side camera will be analyzed frame by frame and the velocity during the impact calculated. A 100 Hz reference signal will be placed on the film so that accurate frame speed can be determined for film analysis. An electronic signal generator provides the calibrated 100-Hz pulse train to light emitting diodes (LEDs) in the high-speed cameras. Illumination of the LEDs exposes a small red dot on the edge of the film, outside the normal field of view. During film analysis, the precise film speed is determined from the number of frames and fractions thereof that pass between two adjacent LED marks.

All the data output described in this section will be presented in a report and submitted to the FRA. The report will also contain general information about the crash test and describe how it was conducted.

9.0 Safety

All Transportation Technology Center, Inc. (TTCI) safety rules will be observed during the preparation and performance of the crash tests. All personnel participating in the tests will be required to comply with these rules when visiting the TTC, including wearing appropriate personal protective equipment. A safety briefing for all test personnel and visitors will be held prior to testing.

























Location	Camera	Camera	Frame	Lens	Lens	F-stop
	View	Serial #	Speed	(mm)	Serial #	
F1	Westside-	Milliken	300	16	570	4.5
	Overall	7332-1				
F2	Overhead-	Milliken	500	10	050	4.0
	Impact	6893				
F3	Eastside –	Milliken	300	25	894154	4.5
	Overall	6970				
F4	Eastside	Milliken	300	25	6821	4.5
		7169				
F5	Eastside	Milliken	300	25	882012	4.5
		7341				
F6	Eastside	Milliken	300	25	14512	4.5
		7486				
F7	Eastside	Milliken	300	12	pentv	4.5
		7348				
F8	Overhead-	Milliken	300	25	1	4.5
	Rear	7410				
F9	Eastside-	Milliken	120	25	048	8.0
	Panning	6967-1				
F10	Eastside-	Locam	500	50	3853	4.0
	Close-up	1280				

APPENDIX B: Camera Set-up Sheet Table B.1 High-Speed Film Camera Set Up

Table B.2 High Speed Film Camera Set-up

Location	Camera View	Camera	Camera	Frame	Lens
		Туре	Serial #	Rate	(mm)
V1	Overhead-Impact	Hi-8	240	30	3.6
V2	Overhead-Rear View	Hi-8	026	30	3.6
V3	Overhead-Front View	Hi-8	248	30	3.6
V4	Southeast-Angle View	Hi-8	044	30	3.6
V5	Eastside-Overall View	8mm	868	30	w/a lens
V6	Eastside-Panning	S-VHS	259	30	8
V7	Northeast-Angle View	3ccd-dig.	455	30	4.2
V8	Overhead-Rear View	Hi-8	321	30	3.6
V9	Northwest-Angle View	VHS	223	30	12
V10	Westside-View	Dig.8	759	30	3.7
V11	Westside-Panning	DV	-	30	-
V12	Westside-Panning HS	DV	167	120	5.0
V13	Westside-Overall View	Hi-8	701	30	w/a lens
V14	Westside-View	Dig.8	690	30	3.7
V15	Southwest-Angle View	Hi-8	857	30	3.6